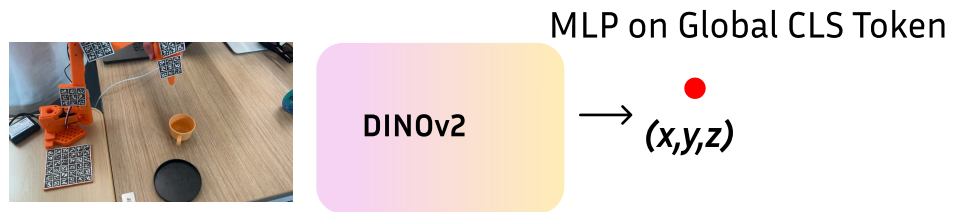
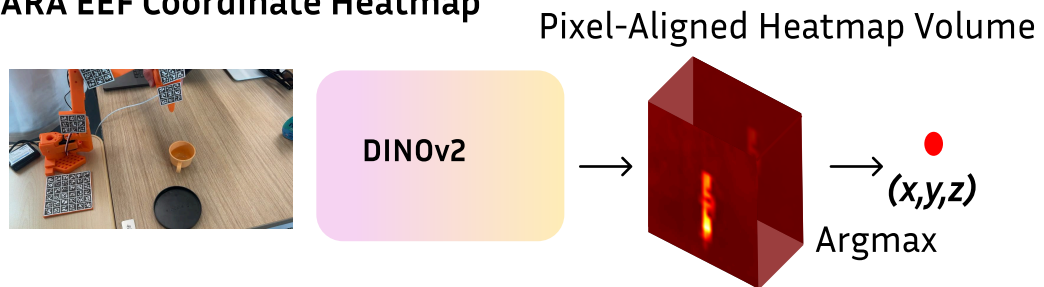


Pixel Aligned Robot Actions (PARA)

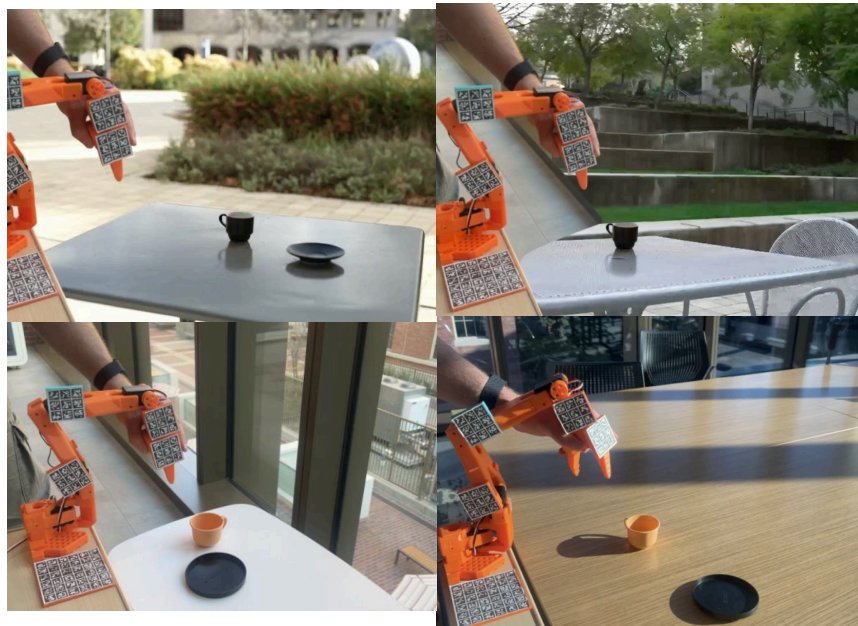
Global EEF Regression



PARA EEF Coordinate Heatmap



Unseen Viewpoints and Environments



Task Success

