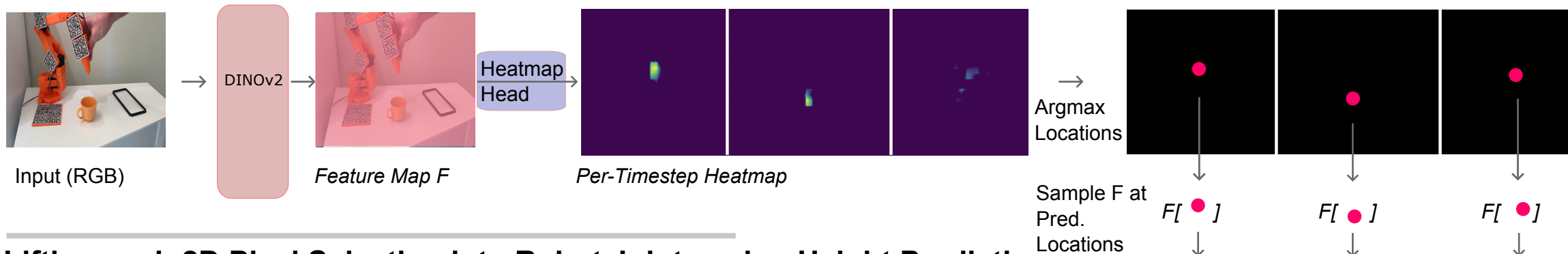


Predicting 2D Pixel Trajectories and Corresponding Height, Rotation, Gripper



Lifting each 2D Pixel Selection into Robot Joints using Height Prediction

Predicted Heatmap

