

## Train: 10 Demos x 4 Viewpoints

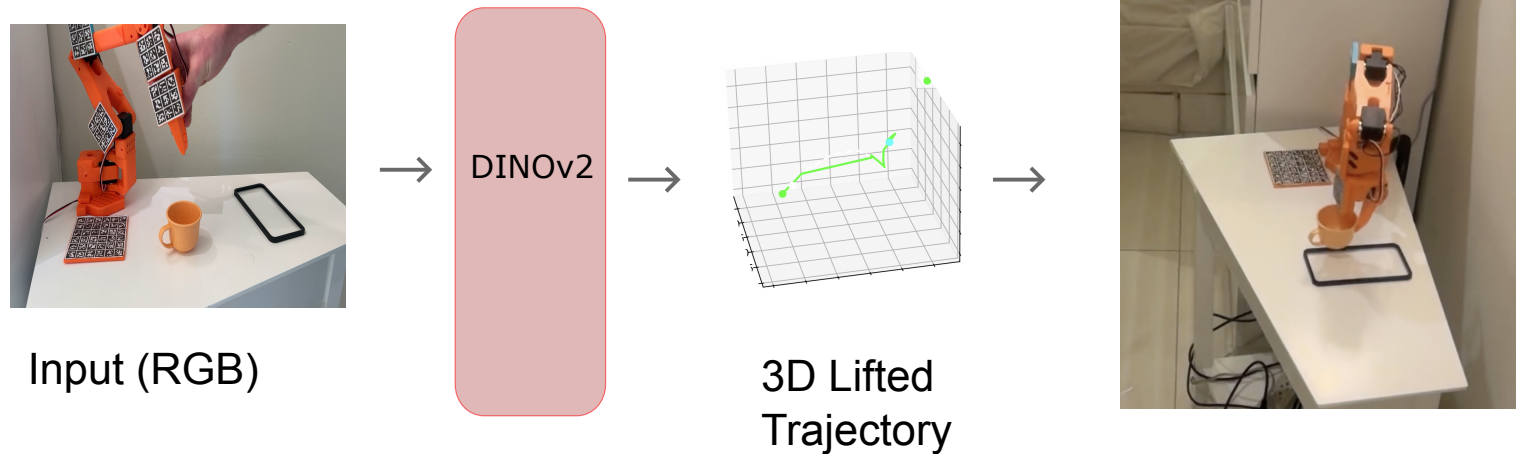


## Test: New Viewpoints and Locations



## Traditional End-Effector Regression

2/10 Success



## Robot Actions as Pixel Selection (Ours)

9/10 Success

